

Hybrid turbulence models for atmospheric flow

A proper comparison with RANS models

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Current issues in atmospheric modeling

- Computationally expensive if accuracy is needed
 - ▶ **Possible solution** : Hybrid models
- Turbulence theory is mainly based on flat terrain studies
 - ▶ i.e. wall-functions are used in complex terrain
 - ▶ **Possible solution** : A different approach for wall treatment in ABL

Proposed turbulence model :

$k - \omega$ SST-SIDDES

(Simplified Improved Delayed Detached-Eddy Simulation)

Objectives

Main research objective :

Thorough validation of the proposed model for use in complex terrain

SOWE 2014 objective :

Validation cases :
-Atmospheric surface-layer*
-Atmospheric boundary-layer*

*Flat rough terrain, neutral stratification and no Coriolis effects

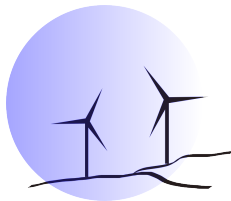
Focusing on comparing with a RANS model

Detached eddy simulation

- **DES** : hybrid model developed for massively separated flows
 - ▶ **URANS** to solve the boundary layer
 - ▶ **LES** outside the boundary layer



- **but** only the boundary layer is important for atmospheric flows
 - ▶ wall-modeled LES → **SIDDES** approach is needed



Proposed turbulence model

$k - \omega$ SST-SIDDES (Gritskevich et al., 2012)

- Hybrid approach based on :

- ▶ SIDDES

- ▶ RANS $k - \omega$ SST (Menter et al., 2003)

- ★ Good results for adverse pressure gradient and separation regions, and its roughness treatment

$$\frac{\partial \bar{u}_i}{\partial t} + \bar{u}_j \frac{\partial \bar{u}_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_j} \left[(\nu + \nu_t) \left(\frac{\partial \bar{u}_i}{\partial x_j} + \frac{\partial \bar{u}_j}{\partial x_i} \right) \right]$$

URANS-mode : \bar{u}_i is the time-average velocity

LES-mode : \bar{u}_i is the filtered velocity

$$\frac{\partial k}{\partial t} + \dots = \tilde{P} - \underbrace{\frac{k^{3/2}}{\tilde{l}}}_{\epsilon}$$

$$\frac{\partial \omega}{\partial t} + \dots$$

In the URANS-mode and LES-mode :

$$\nu_t = \frac{a_1 k}{\max(a_1 \omega, SF_2)}$$

The length scale \tilde{l} will determine the “mode” of the equations locally and varying in time

Length scale definition

Detached Eddy Simulation (DES) (Spalart et al., 1997)

$$\tilde{l}_{DES} \equiv \min(l_{RANS}, l_{LES})$$

****Might yield erroneous results for ABL flows**

Simplified Improved Delayed Detached Eddy Simulation (SIDDES) (Gritskevich et al., 2012)

$$\tilde{l}_{SIDDES} \equiv \tilde{f}_d l_{RANS} + (1 - \tilde{f}_d) l_{LES}$$

Roughness treatment

- $k - \omega$ SST can be integrated down to the wall
 - ▶ wall-functions can be avoided
- The surface roughness is generally accounted by
 - ▶ a modification of the original equations
 - ▶ or a wall-function

$k - \omega$ SST accounts for roughness simply through the boundary conditions of k and ω

Roughness extension (Knopp et al., 2009)

- For fully rough surfaces :

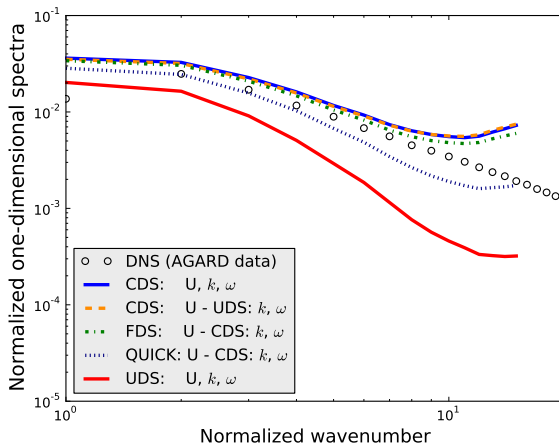
$$k|_{w,ABL} = \frac{u_*^2}{\sqrt{\beta_*}} \quad \omega|_{w,ABL} = \frac{u_*}{\sqrt{\beta_*} \kappa z_0}$$

$$u_*^2 = (\nu + \nu_t) \left. \frac{\partial u}{\partial n} \right|_w$$

- A proper mesh is needed $\rightarrow z_1^+ \approx 0.3$
 - ▶ $z_1^+ \approx 10^4$ for practical ABL grids \rightarrow Can be costly !
 - ▶ Extremely elongated cells close to the wall
 - ★ The *blockMesh* was the main challenge

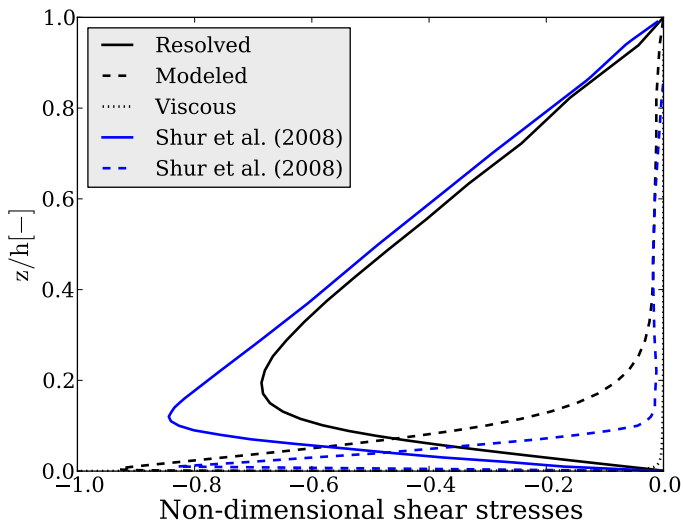
Discretization schemes

- Recommended schemes :
 - ▶ **RANS** : upwind (for stability)
 - ▶ **LES** : central difference (to reduce numerical dissipation)
- Decaying isotropic turbulence test-case (LES-mode) :



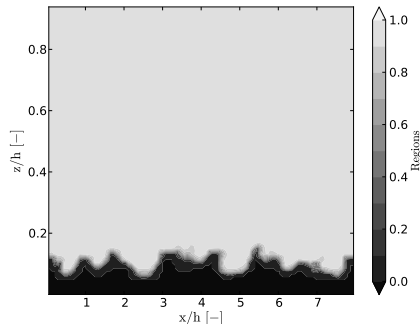
Discretization schemes

- Smooth channel flow using central difference (URANS and LES) :

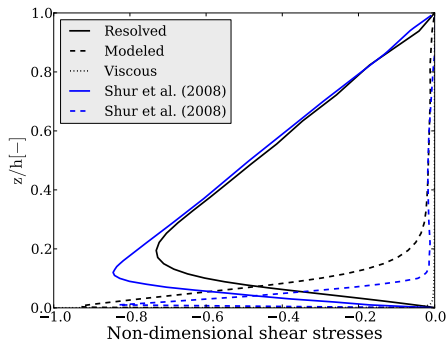


Blended discretization schemes

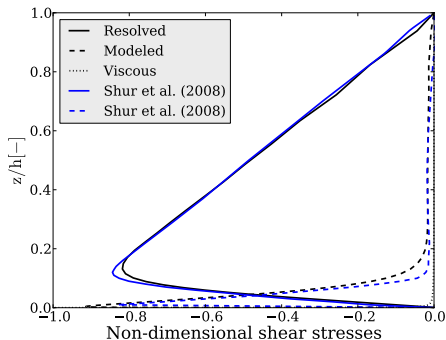
- Blended schemes based on the instantaneous URANS/LES regions
 - ▶ **LES** (light-gray) : 2nd CDS
 - ▶ **URANS** (black) : 2nd UDS



Blended discretization schemes



Blended schemes : U , k and ω



Central schemes : U
Blended schemes : k and ω

How to compare RANS and hybrid simulations ?

Atmospheric surface layer (ASL)

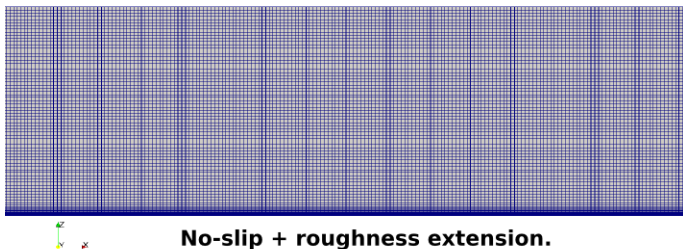
- Monin-Obukhov theory is valid throughout the domain
 - ▶ Logarithmic velocity profile, constant $k\epsilon$, ...
- The height of the ASL is fixed
- Relevant case (?) :
 - ▶ historical reasons
 - ▶ more control over the incident flow on wake studies (Jimenez et al. 2010)

Case 1 : modeling the ASL

- **RANS** : Fixed shear stress at the top boundary
- **LES/hybrids** : Imposing a fixed shear stress is not as evident and some undesired phenomena may occur

Case 1 : Atmospheric surface layer

Fixed shear stress



- Periodic : streamwise and spanwise
- RANS : steady $k - \omega$ SST
- Hybrid : unsteady and taller domain (to account for the buffer layer)
- $z^+ \sim 1$ with a stretching up to 100 m, then uniform $\Delta = 15$ m

How to impose a constant shear stress ?

The value of the wall shear stress,

$$\tau_0 = \rho U_*^2$$

is imposed at the top boundary :

$$\tau_{top} = \rho U_*^2$$

$$\tau_{total} = \tau_{viscous} + \tau_{modeled} + \tau_{resolved}$$

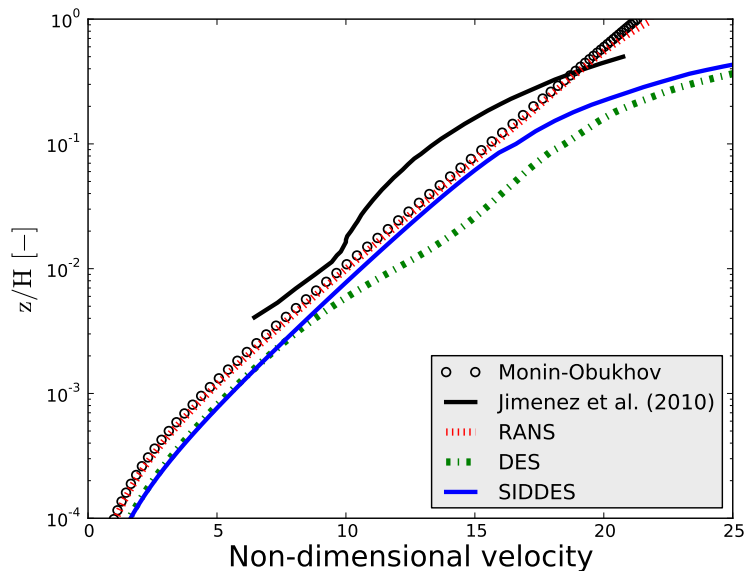
RANS :

$$\tau_{total} \approx \rho \nu_t \frac{\partial \bar{u}}{\partial z}$$

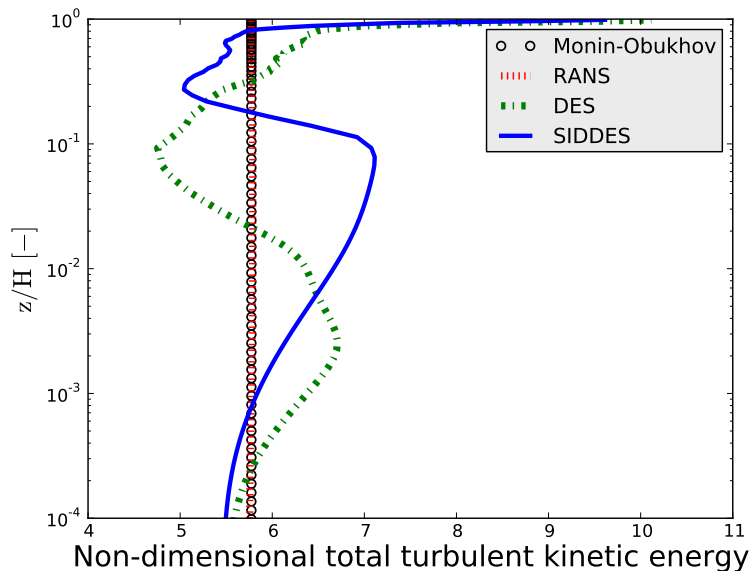
LES :

$$\tau_{total} \approx \rho \nu_t \frac{\partial \bar{u}}{\partial z} - \rho \langle \bar{u}' \bar{w}' \rangle$$

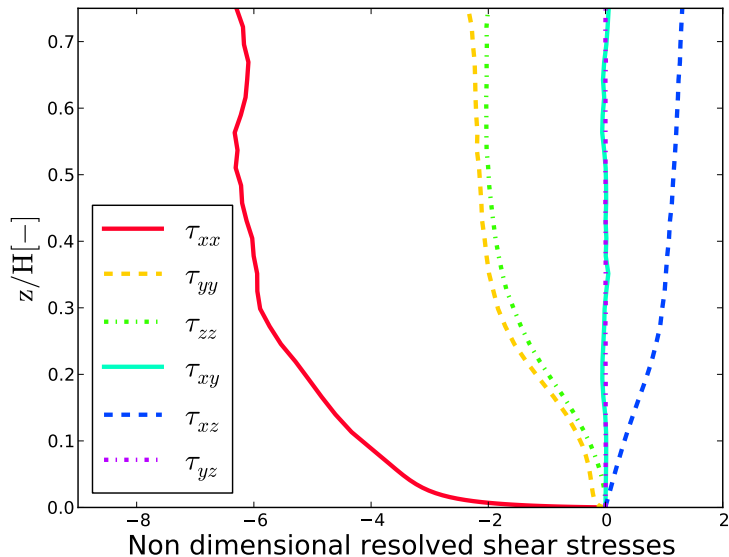
Case 1 : ASL results



Case 1 : ASL results



Case 1 : ASL results - SIDDES



How to compare RANS and hybrid simulations ?

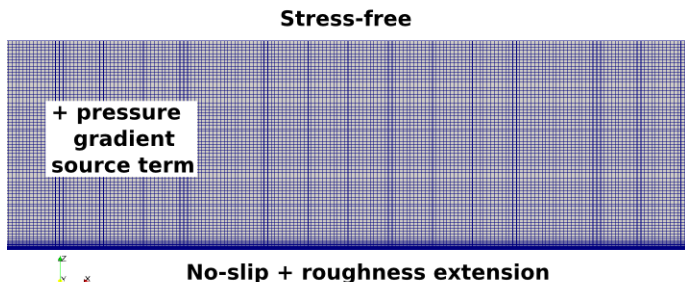
Atmospheric boundary layer (ABL)

- Monin-Obukhov is only valid in $\sim 10\text{-}20\%$ of the domain
- It might be more representative of what happens in reality.

Case 2 : modeling the ABL

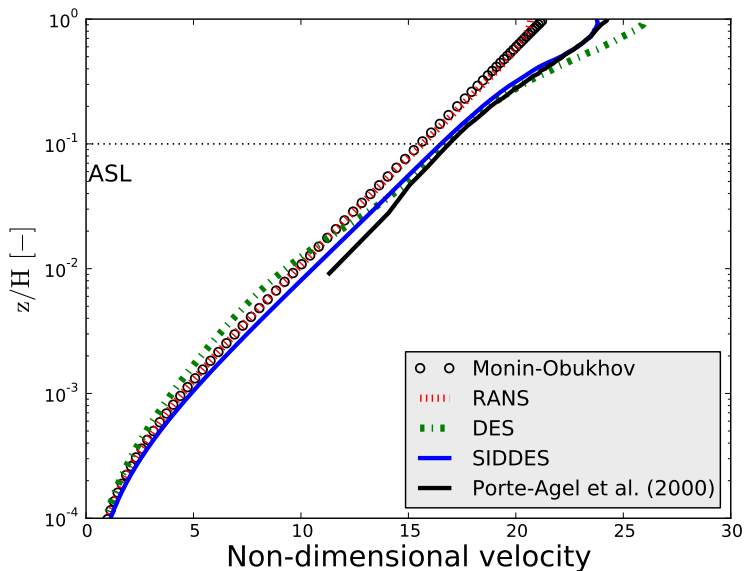
- **RANS** : Introducing a length-scale delimiter (i.e. eddy-viscosity models)
- **LES/hybrids** : Flow is driven by a pressure gradient source term

Case 2 : Atmospheric boundary-layer

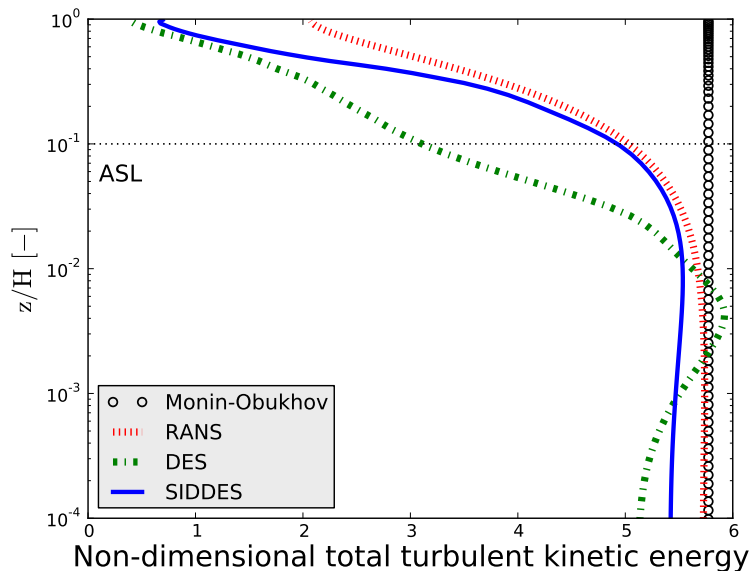


- Periodic : streamwise and spanwise
- RANS : steady and no length-scale delimiter
- $z^+ \sim 1$ with a stretching up to 100 m, then uniform $\Delta = 15$ m

Case 2 : ABL results



Case 2 : ABL results



Conclusion

The $k - \omega$ SST-SIDDES :

- could provide a good compromise between accuracy and computational cost
- avoids the use of wall functions

The flat terrain analysis :

- is crucial to understand the model and its limitation
- is not based on “flat terrain assumptions”

Conclusion

A simple comparison between RANS and the mean values obtained in hybrid simulations prove to be not really straight forward.

Atmospheric surface-layer validation case

- Imposing a shear stress did not yield acceptable results for the hybrid models :
 - ▶ velocity profiles are not correct
 - ▶ but the shear stresses are constant

Atmospheric boundary-layer validation case

- SIDDES gives more accurate results than DES
- Further analysis is needed to compare the hybrid simulations to RANS. (i.e. include length-scale delimiter)
- A more complete grid analysis might be needed, including Brasseur and Wei (2010) criteria to avoid a possible “overshoot”.

Thank you !

Questions ?

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